$$\frac{\text{Goncept}}{\text{Let } G: X \rightarrow X \text{ be a map on a set } X.$$

$$\text{A point } x \in X \text{ for which } GX = X \text{ is called a}$$

$$\frac{\text{Fixed point}}{\text{Fixed point}} \text{ of } G.$$

I Preliminaries

$$\frac{\text{Goncept}(\text{contraction}):}{\text{Let}(M,d) \text{ be a metric space}.}$$

$$A \text{ on ap } G: M \rightarrow M \text{ for which}$$

$$d(O_{X}, O_{Y}) \leq d(X_{Y}) \quad \forall x, y \in M$$
is called a entraction.
If there is a $G < 1$ such that

$$d(O_{X}, O_{Y}) \leq G d(X_{Y}) \quad \forall x, y \in M,$$
then G is called a strict contraction.

<u>Statement</u> (contraction mapping principle): / A strict contraction on a complete metric socce has a muique fixed point. / 2

Sketch: / <u>Uniqueness:</u> // Assume Gx = x, Gy = y $(x, y \in M)$. And $d(x, y) \neq d(Gx, Gy) \neq d(d(x, y))$. Since $d \neq d < A$ it follows that $d(x, y) = d \rightarrow x = 7$.

Existence: // First note: G is automatically autimuans since d(x,y) < G⁻¹E implies d(Gx,Gy) < E.

Next, let
$$x_{0} \in M$$
 be arbitrary. Consider
 $\{x_{n}\}_{n \in \mathbb{N}}$ with $x_{n} = G^{n}x_{0} \stackrel{\text{df}}{=} (\underbrace{0 \cdots 0}_{n \text{ times}}) x_{0}$
 $* \text{ We will shows that } \{x_{n}\}_{n \in \mathbb{N}} \text{ is Cauchy}:$
 $d(x_{n}, x_{n+\lambda}) = d(0x_{n-\lambda}, 0x_{n})$
 $\leq d(x_{n-\lambda}, x_{n})$
 $d(x_{n-\lambda}, x_{n}) = d(0x_{n-\lambda}, x_{n})$
 $\leq d(x_{n-\lambda}, x_{n}) = d(0x_{n-\lambda}, x_{n-\lambda})$
 $\leq d(x_{n-\lambda}, x_{n-\lambda}) = d(0x_{n-\lambda}, x_{n-\lambda})$
 $\leq d(x_{n}, x_{n+\lambda}) \leq d^{2} d(x_{n-\lambda}, x_{n-\lambda})$
 \vdots
 $d(x_{n}, x_{n+\lambda}) \leq d^{2} d(x_{n-\lambda}, x_{n-\lambda})$

for mom $d(x_n, x_m) \leq \sum d(x_n, x_{n-1})$ $\leq \mathsf{C}^{\mathsf{m}} (1 - \mathsf{C})^{-1} \mathsf{d}(\mathsf{x}_{0}, \mathsf{x}_{\lambda}) \xrightarrow{\mathsf{m} \to \infty} \mathsf{d}$ Hence (G"x.] is Cauchy. Since M is complete there is a x ∈ M so that $G^n X \xrightarrow{n \to \infty} X$ By continuity of G $\begin{array}{l} O x = \lim_{n \to \infty} O x_n = \lim_{n \to \infty} x_{n+1} = x_{n+1} \\ \end{array}$

 $\frac{Application:}{\text{Let } f: \mathbb{R} \times \mathbb{R}^{n} \longrightarrow \mathbb{R}^{n} \text{ be continuous.}}$ We are interested in solving $\dot{\gamma}(t) = f(t, \gamma(t)), \quad \gamma(d) = \gamma_{0}.$ Contraction arguments give the existence of $\frac{local}{local} \text{ solutions, i.e. given } \chi \text{ we will find}$ $\gamma: (-S, S) \rightarrow \mathbb{R}^{n}$

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Note: The question whether local solutions can be extended to global solutions is much Aarchier. Differentiation maker functions less smooth, nuless we anxidor only G[∞]-functions. Mis motivates to rewrite the equation of motion in integral form:

$$\gamma(t) = \gamma_{\sigma} + \int_{\sigma}^{t} ds f(s, \gamma(s))$$
 (*)

defined by (E(t,d))(g) = x + Jds f(s,gcs1).

Solving (x) is equivalent to finding a Fixed point of E!

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What is the releasance of 9?

$$\begin{aligned} \text{first} / \hat{i}f g \in \mathcal{G} \text{ then } \mathcal{E}(g) \in \mathcal{G} \text{ since} \\ & \|\mathcal{E}(g) - \gamma_0\| = \|\int_0^{\delta} ds \ f(s, g(s))\| \\ & \leq \int_0^{\delta} ds \|f(s, g(s))\| \\ & \leq S \cdot \max_{\substack{|s| < S}} \|f(s, g(s))\| \\ & \sup_{\substack{|s| < S}} \|s| < \varepsilon \\ & \lim_{\substack{|s| < S}} \|f(s, g(s))\| \\ & \lim_{\substack{|s| < S}} \|g(s) - \gamma_0\| < \varepsilon \end{aligned}$$

Second / g is a complete metric space
ander the supremum norm
$$\|\cdot\|_{\infty}$$
.
For $g_{A}, g_{L} \in G$ ausider
 $\|\mathcal{E}(g_{A}) - \mathcal{E}(g_{L})\|_{\infty} = \|\int_{0}^{t} ds [f(g_{A} z)]_{g(g_{A})}^{g_{A}(g_{A})}\|_{\infty}$
 $\leq \int_{0}^{t} ds \|[f(g_{A} z)]_{g(g_{A})}^{g_{A}(g_{A})}\|_{\infty} \stackrel{lipsdib}{=}$
 $\leq \int_{0}^{t} ds d\|g_{A} - g_{L}\|_{\infty}$ (Itl < 8)
 $\leq d \leq \|g_{A} - g_{L}\|_{\infty}$
Shrinking S are an Ge size that
 $\|\mathcal{E}(g_{A}) - \mathcal{E}(g_{L})\|_{\infty} < \frac{A}{2} \|g_{A} - g_{L}\|_{\infty}$

Anus E is a strict contraction ou g.

The contraction mapping principle then grouts a runique geg sochich satisfies (*).

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Conversely, any solution of (*) must be in g for sufficiently small t and so must agree with the rangue solution in g when t is small. This proves ball existence & rangueness.

Statement: /
Suppose a global solution satisfying the initial
anditions
$$q(t_0) = q_0 > \partial$$
, $P(t_0) = P_0$
does not exist, *i.e.*
the maximal interval on which the
solution with these initial anditions exists
is $[t_0, z)$, $z < \infty$.
Then either

$$\lim_{t \to t} q(t) = \frac{1}{2} \text{ or } \lim_{t \to t} q(t) = \infty$$

Sketch: / By the construction of local solutions and the assumptions made on V: for any compact KCP= (0,00) x R there is a Tk: (qce) pcei) is a muique solution for te (tx-Tx, tx+Tx) with $q(t_{x}) = q_{x} p(t_{x}) = p_{y}$ ~ specified 7 If we cannot extend the solution past E= C, then it annot lie in K for any EST-TK. The remaining task is to show that the statement " (q(1), P(1)) leaves K eventually"

implies that the point mass eventually leaves any compact subsct $G \in (0, \infty)$.

At this stage energy auscrivetion is very ruseful : $H(q(e), P(e)) = H(q_0, r_0) =: E_{n-1}$ If q(t) E C C (0,00), then (q(k), P(k)) E $\left\{ \begin{array}{l} f(\mathbf{k}) : |f(\mathbf{k})| \leq \sqrt{2m(\mathbf{E}_{o} - \inf \mathbf{V}(\mathbf{q}))} \end{array} \right\}$ Thus for all me N there is a to such that $q(k) \notin (\frac{4}{m}, n)$ for t>tn./

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Gencept (complete):/
The classical motion generated by V is called
complete at zero (infinity)
if there is no (90,80)
$$\in \mathbb{R} = (0,00) \times 1\mathbb{R}$$

so that 9(4) runs aff to zero (infinity)
in a finite time./
Statement: /
The classical motion generated by V is
not complete at zero
if and only if V(9) is bounded above
Mear zero./

Sketch: / V is not bounded above at zero
if and only if there is a sequence
$$\{q_n\}_{n \in \mathbb{N}}$$

with $q_n \rightarrow \partial$ so that $V(q_n) \rightarrow \infty$.

By conservation of energy

$$\frac{P^{2}(t)}{am} + V(t) = \frac{P_{c}^{2}}{am} + V(t) = \frac{P_{c}}{am} + V(t)$$

Hence $V(q_{(L)}) \leq E_{Q_{(L)}}$

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2) // Assume: V(q)
$$\leq M$$
 on (0, 1).
Show: V is incomplete
Let $q(t_0) = q_0 = 1$ and choose $\delta < \partial$ and so that
 $E_0 = M + 1$.
By energy onservation
 $\frac{P^2(t)}{2m} \geq 1$
for all t. So the point particle reaches zero
in a finite time. Hence V is incomplete. //

Remark: Jeodesic completeness / Let (M, g) be a spacetime. A <u>curve</u> in M is a smooth mapping X:IcR -> M J has a coordinate system cusisting of the ideality

map u of I. At each $t \in \mathbb{R}$ are can picture the coordinate areator $\frac{d}{du}\Big|_{t} \in T_{t}\mathbb{R}$ as the antit areator at t in the position and another another the position t.

Concept (Velocity orector): // Let Y: I -> H be a curve. The <u>welocity weeter</u> of Y at teI is $\dot{Y}(t) \stackrel{df}{=} dY \left(\frac{d}{du} \right|_{t} \right) \in T_{X(t)} \mathcal{H}. //$

Note that & does not involve geometry! The acceleration & does involve geometry: If $\ddot{v} = \partial$, then \dot{v} is said to be <u>parallel</u>. A geodesic in a spacetime is a curre $\mathcal{X}:\mathcal{I}\longrightarrow\mathcal{H}$ whose vector field & is parallel. Equivalently, geodesics are the aros of varishing acceleration. Statement: // given any fangent vector verfol there is a nuique geodesic &, in c4 such that a) $\dot{\delta}_{ar}(0) = ar$ b) dom (dor) is the largest possible : If d:] -> Il is a geodesic with i(a) = o, then JcI and a = 8, 17.

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A spacetime for which every maximal geodesic is defined on the entire real line is said to be geodesically complete,

Concept (quantum-mediavially complete): /
The potential V(q) is alled qm-complete
if
$$H = \frac{1}{2m} P \cdot P + V(q)$$
 is essentially
self-adjoint on $G_0^{\infty}(o, \infty)$. /

I Formal Gonstructions
Let (U,g) be a globally hyperbolic spacetime.
Choose a time function t and a reator field or
on U so that
$$\nabla_0 t = -1$$
 and the spacelike
surfaces (Ξ)_{teter} are Cauchy hypersurfaces.
Ju most cases $I = J\partial_r tin J$.

Let $G(Z_{E})$ be the set of instantances field configurations $\phi: \mathcal{M} \to \mathbb{K} \in \{R, \mathbb{C}\}$.

Consider (G(Z), D¢) to be a formal measure space. Let $L^{2}(G(\mathbf{Z}_{1}), \mathbf{D}_{1})$ be the C-vector space of wave functionals $\mathbf{Y}_{1}: G(\mathbf{Z}_{1}) \longrightarrow \mathbf{C}$ which are measurable and $\int \mathbf{D}_{2} |\mathbf{Y}_{1}[\mathbf{\Phi}_{1}]|^{2}$ exists.

$$L^{2}(G(Z_{1}, D\phi))$$
 is equipped with the semi norm
 $\|\Psi[\phi]\| = \left\{\int D\phi |\Psi[\phi]|^{2}\right\}^{1/2}$

Yn order to promote His to a morm introduce N(C(Z), Dp) ≇ { 𝒱 ∈ L²(C(Z), Dp) : 𝒱 [\$]=2 D\$p-almost everywrhere }

The physical state space is the quotient space
$$L^2(G(\Xi), D\phi) = L^2(G(\Xi), D\phi) / N(G(\Xi), D\phi).$$

<u>Juterpretation</u>: / If U is a measurable subset of $G(\Xi)$ and V_{U} its indicator functional, then $\|\chi_{U} \Psi[\phi]\|^{2}$

$$E_{\mathfrak{P}_{t}}(\Phi[f]) = \| / \phi[f] \mathcal{P}_{t}[\phi] \|^{2}$$

be well defined.

Ł.

2) Conjugated momentum field operator TT[f] is characterized by Heisenberg's fundamental runcertainty relation

$$\left[\Phi[f_{\lambda}], T[f_{\lambda}]\right] = i(f_{\lambda}, f_{\lambda})$$

Ľ

$$\frac{\text{III} \quad QFT - \text{Gomplete}}{(\text{strongly continuous semigroup of evolution operators}) / \\ A \text{ family } (\text{C}(t,t_o): t,t_o \in I \subset \mathbb{R}^+) \text{ of evolution operators} \\ \text{ Evolution operators} \\ \text{E}(t,t_o): L^2(C(\Sigma_b), D\phi) \rightarrow L^2(C(\Sigma_b), D\phi), \\ \text{T}_b \rightarrow \text{T}_b \stackrel{\text{def}}{=} \text{E}(t,t_o) \text{T}_{t_o} \\ \text{is a strongly continuous semigroup if} \\ (4) \quad \text{E}(t,t_o) = \text{id}_{1^2} \\ (2) \quad \text{E}(t,s) \quad \text{E}(s,t_o) = \text{E}(t,t_o) \\ (3) \quad \text{I} \rightarrow L^2(C(\Sigma_b, D\phi), t \rightarrow \text{E}(t,t_o) \text{T}_{t_o} \\ \text{ is continuous for each } \text{T}_b \in L^2(C(\Sigma_b, D\phi), \text{ operators}) \\ \end{array}$$

A probabilistic interpretation is only possible for a special class of earolution semigroups: <u>Concept</u> (contractive evolution semigroup): / A contractive evolution semigroup is a strongly continuous evolution semigroup and moreover inf $\{C \ge 0: \| \mathcal{E}(t,t_{o}) \oplus \| \leq C \| \mathcal{V}_{o} \|$

We still have

$$E(t,t_{\bullet}) = \exp \{-i \int_{t_{\bullet}}^{t_{\bullet}} ds H[\Phi,\pi;s] \}$$

 $H[\Phi,\pi;g] = \int d\mu \mathcal{H}(\Phi,\pi;g_{z_{\bullet}})$
 f
generator

Question: / Is there as analogue
(auitary, self-adjoint)
$$\cong$$
 (contractive, \cdot)?/
Answer: / Yes:
Gonsider $S \in [L^{\alpha}(C(Z), Ob)]^{k}$ with
 $||S|| = ||Q_{k}||^{\alpha}$.
Formally, Hahn-Bauach guarantees existence.
Concept (accretive): // The generator H
is called accretive if
 $Jm(S(HQ_{k})) \cong d$
for any $Q_{k} \in dom(H)$ and for all $k \in I$. //
(auitary, self-adjoint) \cong (contractive, accretive)/

28 Goncept (
$$9ft$$
-complete): /
)?/ Let Z_0 be a spacelike geodesic baundary of
 (\mathcal{M}, g) located at $t > \partial$.
The spacetime (\mathcal{M}, g) is called $\underline{9ft}$ -complete
if the evolution semigroup is contractive
in (\mathcal{M}, g) and if
 $\|\mathcal{E}(t, t_0)\|_{inp} \xrightarrow{t > \partial} \partial$

$$\frac{\text{Kernel method:}}{\text{Gonsider a Gilinear functional}}$$

$$K_{\pm} : G(\Xi) \times G(\Xi) \longrightarrow \mathbb{C},$$

$$K_{\pm}[\Phi, \Phi] \stackrel{\text{def}}{=} \int_{\text{def}} \int_{\text{d$$

IV Black Holes
IN Black Holes
The kernel is of BKL-type

$$K_{L}(x,y) \approx \frac{i}{t^{e}|ln(k|tin)|} Socy) + less sing.$$

in the vicinity of the geodenic border located
at $k \ge 0$.
Hence,
 $Y_{L} \approx 0$.
So qfL grants no probabilistic support to
the geodenic border. Events cannot poulte
 Σ_{o} and therefore measurement cannot
probe the singularity.